

Worksheet n°1 : mesh, base-flow, global modes, adjoint global modesCodes may be downloaded on: <http://denissipp.free.fr/teaching/Codes/NumStud.zip>

0/ Very short reminder on finite elements

Let us solve the following problem:

$$u - (\partial_{xx}u + \partial_{yy}u) = f$$

$$u = d \text{ on } \Gamma_d$$

$$au + b\partial_n u = c \text{ on } \Gamma_m$$

We consider test functions \tilde{u} satisfying $\tilde{u} = 0$ on Γ_d . After multiplying the governing equation by the test-function, we take an integral over the complete domain:

$$\iint \tilde{u}(u - (\partial_{xx}u + \partial_{yy}u))dxdy = \iint \tilde{u}fdxdy$$

Integrating by parts, we obtain:

$$\iint (\tilde{u}u + \partial_x \tilde{u}\partial_x u + \partial_y \tilde{u}\partial_y u)dxdy - \int (\tilde{u}n_x \partial_x u + \tilde{u}n_y \partial_y u)ds = \iint \tilde{u}fdxdy$$

The boundary term is zero on Γ_d because of $\tilde{u} = 0$. Therefore, taking into account the boundary condition on Γ_m , we have:

$$\iint (\tilde{u}u + \partial_x \tilde{u}\partial_x u + \partial_y \tilde{u}\partial_y u)dxdy - \int_{\Gamma_m} \tilde{u} \left(c - \frac{a}{b}u \right) ds = \iint \tilde{u}fdxdy$$

Rearranging:

$$\iint (\tilde{u}u + \partial_x \tilde{u}\partial_x u + \partial_y \tilde{u}\partial_y u)dxdy + \int_{\Gamma_m} \frac{a}{b} \tilde{u}uds = \iint \tilde{u}fdxdy + \int_{\Gamma_m} \tilde{u}cds$$

Using for example P2 elements for u and \tilde{u} , we obtain the following discretized form (taking into account that $u = d$ on Γ_d):

$$Au = b$$

1/ Generate mesh

In folder Mesh:

FreeFem++ mesh.edp

2/ Base-flow

The base-flow is solution of the following non-linear equation:

$$\frac{1}{2} \mathcal{N}(w_0, w_0) + \mathcal{L}w_0 = 0, \quad \mathcal{N}(w_1, w_2) = \begin{pmatrix} u_1 \cdot \nabla u_2 + u_2 \cdot \nabla u_1 \\ 0 \end{pmatrix}, \quad \mathcal{L} = \begin{pmatrix} -\nu \Delta 0 & \nabla 0 \\ -\nabla \cdot 0 & 0 \end{pmatrix}$$

with the following boundary conditions:

$$(u_0 = 1, v_0 = 0) \text{ on } \Gamma_{in}$$

$$(u_0 = 0, v_0 = 0) \text{ on } \Gamma_{wall}$$

$$(-p_0 n_x + \nu(n_x \partial_x u_0 + n_y \partial_y u_0)) = 0, -p_0 n_y + \nu(n_x \partial_x v_0 + n_y \partial_y v_0) = 0 \text{ on } \Gamma_{out}$$

$$(\partial_y u_0 = 0, v_0 = 0) \text{ on } \Gamma_{lat}$$

The Newton iteration is based on successive solutions of:

$$(\mathcal{N}_w + \mathcal{L})\delta w = -\frac{1}{2} \mathcal{N}(w, w) - \mathcal{L}w \text{ where } \mathcal{N}_w \delta w = \begin{pmatrix} \delta u \cdot \nabla u + u \cdot \nabla \delta u \\ 0 \end{pmatrix}$$

with boundary conditions such that $w + \delta w$ satisfy the above mentioned boundary conditions.

Hence:

$$\begin{aligned} \delta u \partial_x u + \delta v \partial_y u + u \partial_x \delta u + v \partial_y \delta u + \partial_x \delta p - \nu(\partial_{xx} \delta u + \partial_{yy} \delta u) \\ = -u \partial_x u - v \partial_y u - \partial_x p + \nu(\partial_{xx} u + \partial_{yy} u) \end{aligned}$$

$$\begin{aligned} \delta u \partial_x v + \delta v \partial_y v + u \partial_x \delta v + v \partial_y \delta v + \partial_y \delta p - \nu(\partial_{xx} \delta v + \partial_{yy} \delta v) \\ = -u \partial_x v - v \partial_y v - \partial_y p + \nu(\partial_{xx} v + \partial_{yy} v) \end{aligned}$$

$$-\partial_x \delta u - \partial_y \delta v = \partial_x u + \partial_y v$$

with:

$$(\delta u = 1 - u, \delta v = -v) \text{ on } \Gamma_{in}$$

$$(\delta u = -u, \delta v = -v) \text{ on } \Gamma_{wall}$$

$$\begin{aligned} (-\delta p n_x + \nu(n_x \partial_x \delta u + n_y \partial_y \delta u)) = p n_x - \nu(n_x \partial_x u + n_y \partial_y u), -\delta p n_y + \nu(n_x \partial_x \delta v + n_y \partial_y \delta v) \\ = p n_y - \nu(n_x \partial_x v + n_y \partial_y v) \text{ on } \Gamma_{out} \\ (\partial_y \delta u = -\partial_y u, \delta v = -v) \text{ on } \Gamma_{lat} \end{aligned}$$

Show that the weak form of these equations is (with \tilde{w} as the test-function satisfying $\tilde{u} = \tilde{v} = 0$ on Γ_{in} and Γ_{wall} and $\tilde{v} = 0$ on Γ_{lat})

$$\begin{aligned} \iint (\tilde{u}(\delta u \partial_x u + \delta v \partial_y u + u \partial_x \delta u + v \partial_y \delta u) + \tilde{v}(\delta u \partial_x v + \delta v \partial_y v + u \partial_x \delta v + v \partial_y \delta v) - \delta p(\partial_x \tilde{u} + \partial_y \tilde{v}) \\ + v(\partial_x \tilde{u} \partial_x \delta u + \partial_y \tilde{u} \partial_y \delta u + \partial_x \tilde{v} \partial_x \delta v + \partial_y \tilde{v} \partial_y \delta v) - \tilde{p}(\partial_x \tilde{u} + \partial_y \tilde{v}) \\ + \partial_y \delta v)) dxdy = \iint (-\tilde{u}(u \partial_x u + v \partial_y u) - \tilde{v}(u \partial_x v + v \partial_y v) + p(\partial_x \tilde{u} + \partial_y \tilde{v}) \\ - v(\partial_x \tilde{u} \partial_x u + \partial_y \tilde{u} \partial_y u + \partial_x \tilde{v} \partial_x v + \partial_y \tilde{v} \partial_y v) + \tilde{p}(\partial_x u + \partial_y v)) dxdy \end{aligned}$$

After discretization (taking into account all the Dirichlet boundary-conditions), we obtain:

$$A\delta w = b$$

In folder BF:

$$\text{vi param.txt} \quad // \text{target Reynolds number, here Re=100}$$

$$\text{FreeFem++ init.edp} \quad // \text{generate initial guess solution, here zero flowfield}$$

$$\text{FreeFem++ newton.edp} \quad // \text{compute base-flow}$$

$$\text{FreeFem++ plotUvp.edp} \quad // \text{show base-flow at Re=100}$$

3/ Global modes

The global modes are the structures such that:

$$\lambda B\hat{w} + (\mathcal{N}_{w_0} + \mathcal{L})\hat{w} = 0, \quad B = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

where $(\mathcal{N}_{w_0} + \mathcal{L})$ is the linearized Navier-Stokes operator:

$$(\mathcal{N}_{w_0} + \mathcal{L})\hat{w} = \begin{pmatrix} \hat{u}\partial_x u_0 + \hat{v}\partial_y u_0 + u_0\partial_x \hat{u} + v_0\partial_y \hat{u} + \partial_x \hat{p} - \nu(\partial_{xx}\hat{u} + \partial_{yy}\hat{u}) \\ \hat{u}\partial_x v_0 + \hat{v}\partial_y v_0 + u_0\partial_x \hat{v} + v_0\partial_y \hat{v} + \partial_y \hat{p} - \nu(\partial_{xx}\hat{v} + \partial_{yy}\hat{v}) \\ -(\partial_x \hat{u} + \partial_y \hat{v}) \end{pmatrix}$$

$(\mathcal{N}_{w_0} + \mathcal{L})$ acts on a subspace of functions \hat{w} satisfying the following boundary conditions $(\tilde{*})$

$$(\hat{u} = 0, \hat{v} = 0) \text{ on } \Gamma_{in} \text{ and } \Gamma_{wall}$$

$$(-\hat{p}n_x + \nu(n_x\partial_x \hat{u} + n_y\partial_y \hat{u})) = 0, \quad (-\hat{p}n_y + \nu(n_x\partial_x \hat{v} + n_y\partial_y \hat{v})) = 0 \text{ on } \Gamma_{out}$$

$$(\partial_y \hat{u} = 0, \hat{v} = 0) \text{ on } \Gamma_{lat}$$

Show that the weak form of these equations is (with \tilde{w} as the test-function satisfying $\tilde{u} = \tilde{v} = 0$ on Γ_{in} and Γ_{wall} and $\tilde{v} = 0$ on Γ_{lat}):

$$\iint (\tilde{u}(-\hat{u}\partial_x u_0 - \hat{v}\partial_y u_0 - u_0\partial_x \hat{u} - v_0\partial_y \hat{u}) + (\partial_x \tilde{u})\hat{p} - \nu(\partial_x \tilde{u}\partial_x \hat{u} + \partial_y \tilde{u}\partial_y \hat{u}) + \tilde{v}(-\hat{u}\partial_x v_0 - \hat{v}\partial_y v_0 - u_0\partial_x \hat{v} - v_0\partial_y \hat{v}) + (\partial_y \tilde{v})\hat{p} - \nu(\partial_x \tilde{v}\partial_x \hat{v} + \partial_y \tilde{v}\partial_y \hat{v}) + \tilde{p}(\partial_x \hat{u} + \partial_y \hat{v})) dx dy = \lambda \iint (\tilde{u}\hat{u} + \tilde{v}\hat{v}) dx dy$$

With a finite element-discretization:

$$A\hat{w} = \lambda B\hat{w}$$

In folder Eigs:

FreeFem++ eigen.edp:

4/ Definition of adjoint operator.

The adjoint operator $(\widetilde{\mathcal{N}}_{w_0} + \widetilde{\mathcal{L}})$ is the operator satisfying for all \hat{w} and \tilde{w} the following relations:

$$\langle \tilde{w}, (\mathcal{N}_{w_0} + \mathcal{L})\hat{w} \rangle = \langle (\widetilde{\mathcal{N}}_{w_0} + \widetilde{\mathcal{L}})\tilde{w}, \hat{w} \rangle$$

Here \hat{w} is in the subspace satisfying the boundary conditions $(\tilde{*})$.

Determine the adjoint operator $(\widetilde{\mathcal{N}}_{w_0} + \widetilde{\mathcal{L}})$ and the boundary conditions $(\tilde{*})$ that \tilde{w} satisfies.

Solution:

$$(\widetilde{\mathcal{N}}_{w_0} + \widetilde{\mathcal{L}})\tilde{w} = \begin{pmatrix} -u_0\partial_x \tilde{u} - v_0\partial_y \tilde{u} + \tilde{u}\partial_x u_0 + \tilde{v}\partial_y v_0 + \partial_x \tilde{p} - \nu(\partial_{xx}\tilde{u} + \partial_{yy}\tilde{u}) \\ -u_0\partial_x \tilde{v} - v_0\partial_y \tilde{v} + \tilde{u}\partial_x u_0 + \tilde{v}\partial_y v_0 + \partial_y \tilde{p} - \nu(\partial_{xx}\tilde{v} + \partial_{yy}\tilde{v}) \\ -(\partial_x \tilde{u} + \partial_y \tilde{v}) \end{pmatrix}$$

$$(\tilde{u} = 0, \tilde{v} = 0) \text{ on } \Gamma_{in} \text{ and } \Gamma_{wall}$$

$$\begin{aligned} (-\tilde{p}n_x + \nu\partial_x \tilde{u}n_x + \nu\partial_y \tilde{u}n_y) &= -\tilde{u}u_0n_x - \tilde{v}v_0n_y, \quad -\tilde{p}n_y + \nu\partial_x \tilde{v}n_x + \nu\partial_y \tilde{v}n_y \\ &= -\tilde{v}u_0n_x - \tilde{v}v_0n_y \text{ on } \Gamma_{out} \end{aligned}$$

$$(\partial_y \tilde{u} = 0, \tilde{v} = 0) \text{ on } \Gamma_{lat}$$

5/ The adjoint global modes are solution of the following eigen-problem :

$$\lambda B\tilde{w} + (\widetilde{\mathcal{N}}_{w_0} + \widetilde{\mathcal{L}})\tilde{w} = 0$$

with the above mentioned boundary conditions.

Show that the weak form of these equations is:

$$\begin{aligned} \iint (\tilde{u}(u_0\partial_x \tilde{u} + v_0\partial_y \tilde{u} - \tilde{u}\partial_x u_0 - \tilde{v}\partial_x v_0) + (\partial_x \tilde{u})\tilde{p} - \nu(\partial_x \tilde{u}\partial_x \tilde{u} + \partial_y \tilde{u}\partial_y \tilde{u}) + \tilde{v}(u_0\partial_x \tilde{v} + v_0\partial_y \tilde{v} - \tilde{u}\partial_y u_0 - \tilde{v}\partial_y v_0) \\ + (\partial_y \tilde{v})\tilde{p} - \nu(\partial_x \tilde{v}\partial_x \tilde{v} + \partial_y \tilde{v}\partial_y \tilde{v}) + \tilde{p}(\partial_x \tilde{u} + \partial_y \tilde{v})) dx dy \\ - \int_{\Gamma_{out}} \tilde{u}(\tilde{u}u_0n_x + \tilde{v}v_0n_y) ds - \int_{\Gamma_{out}} \tilde{v}(\tilde{v}u_0n_x + \tilde{v}v_0n_y) ds = \lambda \iint (\tilde{u}\tilde{u} + \tilde{v}\tilde{v}) dx dy \end{aligned}$$

After discretization, we obtain:

$$\tilde{A}\tilde{w} = \lambda B\tilde{w}$$

Complete program eigenadj.edp (look for ??? in this file) to compute the adjoint global modes.

6/ Compute the angle between the direct and adjoint global modes. Check bi-orthogonality of direct and adjoint global modes.

7/ Modify program eigen.edp to solve the eigen-problem:

$$A^*\tilde{w}' = \mu B\tilde{w}'$$

where A^* designates the transconjugate of matrix A. Compare \tilde{w}' and \tilde{w} .

Show that: $(\mu^* - \lambda)\tilde{w}'^* B\tilde{w} = 0$. Interpret the results.

8/ DNS simulations. We consider the Navier-Stokes equations in perturbative form: $w(t) = w_0 + w'(t)$:

$$\begin{cases} \partial_t u' + u' \cdot \nabla u_0 + u_0 \cdot \nabla u' + u' \cdot \nabla u' \\ \nabla \cdot u' \end{cases} = \begin{cases} -\nabla p' + \nu \Delta u' \\ 0 \end{cases}$$

A first-order semi-implicit discretization in time yields:

$$\begin{cases} \frac{u^{n+1} - u^n}{\Delta t} + u^{n+1} \cdot \nabla u_0 + u_0 \cdot \nabla u^{n+1} + u^n \cdot \nabla u^n \\ \nabla \cdot u^{n+1} \end{cases} = \begin{cases} -\nabla p^{n+1} + \nu \Delta u^{n+1} \\ 0 \end{cases}$$

This may be re-arranged into:

$$\begin{cases} \frac{u^{n+1}}{\Delta t} + u^{n+1} \cdot \nabla u_0 + u_0 \cdot \nabla u^{n+1} + \nabla p^{n+1} - \nu \Delta u^{n+1} \\ \nabla \cdot u^{n+1} \end{cases} = \begin{cases} \frac{u^n}{\Delta t} - u^n \cdot \nabla u^n \\ 0 \end{cases}$$

Show that the weak form with \tilde{w} as the test-function is:

$$\begin{aligned}
& \iint \left(\tilde{u} \left(\frac{u^{n+1}}{\Delta t} + u^{n+1} \partial_x u_0 + v^{n+1} \partial_y u_0 + u_0 \partial_x u^{n+1} + v_0 \partial_y u^{n+1} \right) - (\partial_x \tilde{u}) p^{n+1} + v (\partial_x \tilde{u} \partial_x u^{n+1} + \partial_y \tilde{u} \partial_y u^{n+1}) \right. \\
& \quad \left. + \tilde{v} \left(\frac{v^{n+1}}{\Delta t} + u^{n+1} \partial_x v_0 + v^{n+1} \partial_y v_0 + u_0 \partial_x v^{n+1} + v_0 \partial_y v^{n+1} \right) - (\partial_y \tilde{v}) p^{n+1} \right. \\
& \quad \left. + v (\partial_x \tilde{v} \partial_x v^{n+1} + \partial_y \tilde{v} \partial_y v^{n+1}) + \tilde{p} (\partial_x u^{n+1} + \partial_y v^{n+1}) \right) dx dy \\
& = \iint \left(\frac{\tilde{u} u^n}{\Delta t} - \tilde{u} (u^n \cdot \nabla u^n) + \frac{\tilde{v} v^n}{\Delta t} - \tilde{v} (v^n \cdot \nabla v^n) \right) dx dy
\end{aligned}$$

After spatial discretization, we obtain:

$$Aw^{n+1} = b$$

In folder DNS,

```

FreeFem++ init.edp      // Initial condition = real part of unit energy eigenvector in ..//Eigs
FreeFem++ dns.edp       // Launch linearized DNS simulation
Octave plotlinlog('out_0.txt',1,2,1)    // plot perturbation energy as a function of time
Octave plotlinlin('out_0.txt',1,3,1)     // plot u-velocity in wake as a function of time
FreeFem++ plotUvvp.edp    // Plot flowfield after 100 time steps

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9/ Perform a linearized DNS simulation with a unit energy adjoint flowfield as initial condition.
 Compare perturbation energy as a function of time with results obtained in 8/ Relate this result to the angle computed in 6/

10/ Perform a non-linear simulation to observe saturation (switch NL to 1 in dns.edp).

11/ Vary the Reynolds number, find critical Reynolds number with stability analyses and observe saturation amplitudes with non-linear simulations as a function of Reynolds number in the range $40 < Re < 100$.

Worksheet n°2: Multiple time-scale analysis and amplitude equationsCodes may be downloaded on: <http://denissipp.free.fr/teaching/Codes/NumStud3.zip>**1/ Direct numerical simulation of cylinder flow at Re=100**

We solve the unsteady Navier-Stokes equations in perturbative form ($w := w_0 + \hat{w}$) around a cylinder flow at $Re = \nu^{-1} = 100$. The initial condition is the real part of a small amplitude unstable global mode.

$$\mathcal{B}\partial_t w + \mathcal{N}_{w_0} w + \mathcal{L}w = -\frac{1}{2}\mathcal{N}(w, w)$$

$$w(0) = \alpha \text{Re}(\hat{w})$$

with :

$$w = \begin{pmatrix} u \\ v \\ p \end{pmatrix}, \mathcal{B} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \mathcal{N}(w_1, w_2) = \begin{pmatrix} u_1 \cdot \nabla u_2 + u_2 \cdot \nabla u_1 \\ 0 \end{pmatrix}, \mathcal{N}_{w_0} w = \mathcal{N}(w_0, w),$$

$$\mathcal{L} = \begin{pmatrix} -\nu \Delta & \nabla \\ -\nabla \cdot & 0 \end{pmatrix}$$

The base-flow and the global mode are defined by:

$$\frac{1}{2}\mathcal{N}(w_0, w_0) + \mathcal{L}w_0 = 0$$

$$\lambda \mathcal{B}\hat{w} + (\mathcal{N}_{w_0} + \mathcal{L})\hat{w} = 0$$

In DNS/Mesh:

FreeFem++ mesh.edp

In DNS/BF:

FreeFem++ init.edp

FreeFem++ newton.edp

In DNS/Eigs:

FreeFem++ eigen.edp

In DNS/DNS:

FreeFem++ init.edp // generate initial condition from small amplitude global mode

FreeFem++ dns.edp // launch DNS simulation

Octave plotlinlog('out_0.txt',1,2,1) // represent energy as a function of time in fig 1

Octave plotlinlin('out_0.txt',1,4,2) // represent v velocity as a function of time

2/ Van der Pol Oscillator: multiple time-scale analysis

The Van der Pol Oscillator corresponds to the following governing equations:

$$w'' + \omega_0^2 w = 2\delta w' - w^2 w'$$

$$w(0) = w_I, w'(0) = 0$$

where the $(\cdot)'$ is the time-derivative, w_I is the initial condition, ω_0 the frequency and δ the instability strength. Here, we choose: $\omega_0 = 10$, $\delta = 0.3$ and $w_I = 0.01$.

2a/ Numerical time-integration

We integrate in time the above equations. For this,

In VanDerPol:

Octave pkg load all // load external packages for time integration, Fourier analysis, etc.

Octave vdp // integrate in time unforced Van der Pol equations

2b/ One time-scale approach

We try to approximate the solution by considering a small instability strength: $\delta = \delta\epsilon$, with $\epsilon \ll 1$ and $\delta = O(1)$. We look for an approximation of the solution with an expansion of the form:

$$w = \epsilon^{\frac{1}{2}}y \text{ and } y = y_0 + \epsilon y_1 + \dots$$

We first try with only one time-scale: $y(t) = y_0(t) + \epsilon y_1(t) + \dots$

The second-order solution is given by:

$$w = (\tilde{A}e^{i\omega_0 t} + \text{c. c.}) + \left(\frac{-3\tilde{A}^3 + 12\delta\tilde{A}}{8\omega_0} ie^{i\omega_0 t} + \frac{i\tilde{A}^3}{8\omega_0} e^{3i\omega_0 t} - (2\delta\tilde{A} - \tilde{A}^3) \left(\frac{1 + 2i\omega_0 t}{4\omega_0} \right) ie^{i\omega_0 t} + \text{c. c.} \right)$$

$$\tilde{A} = \frac{w_I}{2}$$

To represent this solution, in VanDerPol:

Octave clf // clear all figures

Octave vdp // integrate in time unforced Van der Pol equations

Octave vdp_tlr // show first and second order approximations with one time-scale

2c/ Two time-scales approach

The two time-scale first-order solution is given by:

$$w(t) = (\tilde{A}e^{i\omega_0 t} + \text{c. c.})$$

with:

$$\frac{d\tilde{A}}{dt} = \tilde{\delta}\tilde{A} - \frac{1}{2}\tilde{A}^3$$

$$\tilde{A}(0) = \frac{w_I}{2}$$

To represent this solution, in VanDerPol:

```
Octave clf      // clear all figures
Octave vdp      // integrate in time unforced Van Der Pol equations
Octave vdp_tlr // show first and second order approximations with one time-scale
Octave vdp_mts // show first and second order approximations with two time-scales
```

3/ Van der Pol Oscillator with harmonic forcing

We consider the forced Van der Pol oscillator:

$$w'' + \omega_0^2 w = 2\tilde{\delta}w' - w^2 w' + \tilde{E} \cos \omega_f t,$$

where ω_f and \tilde{E} are respectively the forcing frequency and the forcing amplitude. Here, we choose: $\omega_f = 25$ and $\tilde{E} = 600$. The first-order two time-scale solution is given by:

$$w(t) = 2\tilde{A} \cos(\omega_0 t + \phi) + \frac{\tilde{E}}{\omega_0^2 - \omega_f^2} \cos \omega_f t$$

with:

$$\frac{d\tilde{A}}{dt} = \left[\tilde{\delta} - \frac{1}{4} \left(\frac{\tilde{E}}{\omega_0^2 - \omega_f^2} \right)^2 \right] \tilde{A} - \frac{1}{2} \tilde{A}^3$$

To represent this solution, in VanDerPol:

```
Octave clf      // clear all figures
Octave vdpf     // integrate in time unforced Van Der Pol equations
```

Vary the forcing amplitude \tilde{E} from 0 to 600 and observe in each case the resulting frequency spectrum.

4/ Forced Navier-Stokes equations

We consider the Navier-Stokes equation in perturbative form ($w := w_0 + w$) with a forcing term acting on the momentum equations:

$$\mathcal{B}\partial_t w + \mathcal{N}_{w_0} w + \mathcal{L}w = \tilde{\delta}\mathcal{M}(w_0 + w) - \frac{1}{2}\mathcal{N}(w, w) + (\tilde{E}e^{i\omega_f t} f + \text{c. c.})$$

Here:

$$w = \begin{pmatrix} u \\ v \\ p \end{pmatrix}, \quad \mathcal{L} = \begin{pmatrix} -v_c \Delta & \nabla \cdot \\ -\nabla \cdot & 0 \end{pmatrix}, \quad \mathcal{M} = \begin{pmatrix} -\Delta & 0 \\ 0 & 0 \end{pmatrix}.$$

The viscosity v has been replaced by $v = v_c - \tilde{\delta}$, where v_c is the critical viscosity which achieves marginal stability of the linear dynamics $Re_c = v_c^{-1} = 46.6$.

The base-flow is given by:

$$\frac{1}{2}\mathcal{N}(w_0, w_0) + \mathcal{L}w_0 = 0,$$

while \tilde{E} and ω_f correspond respectively to the forcing amplitude and forcing frequency. The forcing structure f (acting solely on the momentum equations, so that $\mathcal{B}f = f$) is also given.

In the following, we consider a slightly supercritical regime (the Reynolds number is slightly above the critical Reynolds number):

$$\tilde{\delta} = \epsilon\delta, \quad \epsilon \ll 1, \quad \delta = O(1),$$

and a small- amplitude forcing, which scales as:

$$\tilde{E} = \epsilon^{\frac{1}{2}}E, \quad E = O(1).$$

We look for an approximation of the solution under the form:

$$w = \epsilon^{\frac{1}{2}} \left(y_0(t, \tau = \epsilon t) + \epsilon^{\frac{1}{2}} y_1(t, \tau = \epsilon t) + \epsilon^1 y_1(t, \tau = \epsilon t) + \dots \right)$$

The second-order solution is given by:

$$w = (\tilde{A}e^{i\omega_c t} y_A + \text{c. c.}) + (\tilde{E}e^{i\omega_f t} y_E + \text{c. c.}) + \tilde{\delta}w_\delta + (\tilde{A}^2 e^{2i\omega_c t} y_{AA} + \text{c. c.}) + |\tilde{A}|^2 y_{A\bar{A}} + |\tilde{E}|^2 y_{EE} + (\tilde{A}\tilde{E}e^{i(\omega_c + \omega_f)t} y_{AE} + \text{c. c.}) + (\tilde{A}\bar{\tilde{E}}e^{i(\omega_c - \omega_f)t} y_{A\bar{E}} + \text{c. c.}) + \dots$$

With :

$$i\omega_c \mathcal{B}y_A + \mathcal{N}_{w_0} y_A + \mathcal{L}y_A = 0$$

$$i\omega_f \mathcal{B}y_E + \mathcal{N}_{w_0} y_E + \mathcal{L}y_E = f$$

$$\mathcal{N}_{w_0} y_\delta + \mathcal{L}y_\delta = \mathcal{M}y_0$$

$$2i\omega_c \mathcal{B}y_{AA} + \mathcal{N}_{w_0} y_{AA} + \mathcal{L}y_{AA} = -\frac{1}{2}\mathcal{N}(y_A, y_A)$$

$$\mathcal{N}_{w_0} y_{A\bar{A}} + \mathcal{L}y_{A\bar{A}} = -\mathcal{N}(y_A, \bar{y}_A)$$

$$\mathcal{N}_{w_0} y_{EE} + \mathcal{L}y_{EE} = -\mathcal{N}(y_E, \bar{y}_E)$$

$$2i(\omega_c + \omega_f) \mathcal{B}y_{AE} + \mathcal{N}_{w_0} y_{AE} + \mathcal{L}y_{AE} = -\mathcal{N}(y_A, y_E)$$

$$2i(\omega_c - \omega_f) \mathcal{B}y_{A\bar{E}} + \mathcal{N}_{w_0} y_{A\bar{E}} + \mathcal{L}y_{A\bar{E}} = -\mathcal{N}(y_A, \bar{y}_E)$$

And:

$$\frac{d\tilde{A}}{dt} = \lambda\delta\tilde{A} - \mu\tilde{A}|\tilde{A}|^2 - \pi\tilde{A}|\tilde{E}|^2$$

where:

$$\lambda = \langle \tilde{y}_A, \mathcal{M}y_A \rangle - \langle \tilde{y}_A, \mathcal{N}(y_A, y_\delta) \rangle$$

$$\mu = \langle \tilde{y}_A, \mathcal{N}(y_A, y_{A\bar{A}}) + \mathcal{N}(\bar{y}_A, y_{AA}) \rangle$$

$$\pi = \langle \tilde{y}_A, \mathcal{N}(y_A, y_{EE}) + \mathcal{N}(y_E, y_{AE}) + \mathcal{N}(y_E, y_{AE}) \rangle$$

$$-i\omega_c \mathcal{B}\tilde{y}_A + \tilde{\mathcal{N}}_{w_0}\tilde{y}_A + \tilde{\mathcal{L}}\tilde{y}_A = 0$$

$$\langle \tilde{y}_A, \mathcal{B}y_A \rangle = 1$$

4a/ In AmplEq/Mesh:

FreeFem++ mesh.edp // generate mesh

In AmplEq/BF:

FreeFem++ init.edp // generate initial guess for Newton iterations

FreeFem++ newton.edp // Newton iteration

In AmplEq/Eigs:

FreeFem++ eigen.edp // compute global mode

FreeFem++ eigenadj.edp // compute adjoint global mode

FreeFem++ norm.edp // generate scaled adjoint global mode

In AmplEq/WNL:

FreeFem++ udelta.edp // generate modification of base-flow due to increase in Reynolds number

FreeFem++ uAA.edp // generate second harmonic due to interaction of global mode with himself

FreeFem++ uAb.edp // generate zero-harmonic due to interaction of global mode with adjoint of himself

FreeFem++ lambda.edp // compute λ coefficient of Stuart-Landau equation

FreeFem++ mu.edp // compute μ coefficient of Stuart-Landau equation

FreeFem++ forcing.edp // define external forcing (spatial structure and frequency)

FreeFem++ uE.edp

// compute response due to external forcing

FreeFem++ uAE.edp

// compute AE-harmonic due to interaction of response to external forcing with global mode

4b/ Complete program uAEb.edp to compute the $A\bar{E}$ harmonic due to the interaction of the global mode with the adjoint of the response due to external forcing.

4c/ Complete program uEEb.edp to compute the zero-harmonic due to the interaction of the external forcing response with the conjugate of himself.

4d/ Complete program pi.edp to compute the π coefficient.

5/ Forced Direct numerical simulation

We integrate in time the forced Navier-Stokes equations at $Re = \nu^{-1} = 100$:

$$\mathcal{B}\partial_t w + \mathcal{N}_{w_0} w + \mathcal{L}w = -\frac{1}{2}\mathcal{N}(w, w) + (\tilde{E}e^{i\omega_f t} f + \text{c.c})$$

where:

$$w = \begin{pmatrix} u \\ v \\ p \end{pmatrix}, \mathcal{L} = \begin{pmatrix} -\nu \Delta & \nabla \cdot \\ -\nabla \cdot & 0 \end{pmatrix}$$

In DNS/DNS:

FreeFem++ dnsf.edp // launch forced DNS simulation

Octave plotlinlog('out_4000.txt', 1, 2, 1) // represent energy as a function of time in fig 1

Octave plotlinlin('out_4000.txt', 1, 4, 2) // represent v velocity as a function of time in fig 2

Octave spectrum // compare spectrum with and without control